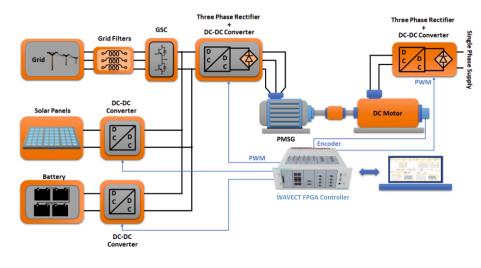


Micro Grid





Key Functionalities

Microgrid setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- Operation of Grid Side converter
- Integration of Power source on to live Grid
- Grid PLL synchronization
- Modeling of Grid Side Filters
- Study and Modeling of MPPT algorithms for Renewable energy setup
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

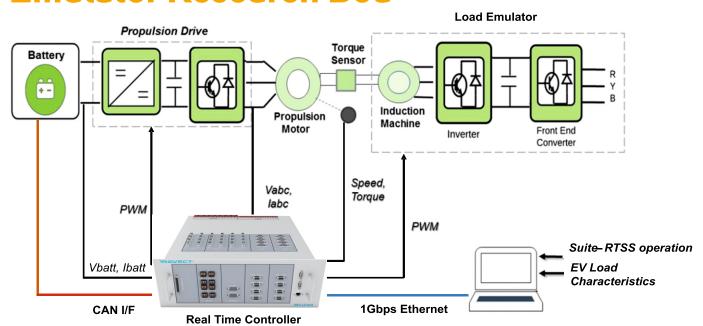
System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

Potential list of Experiments & Research scope

- Reactive Power control on to the Live Grid and for local reactive power compensation
- THD measurement and Analysi
- Load demand management
- · Islanded operation Schemes and Islanding Detection
- Distributed energy source managemen
- Microgrid protection and contro
- Microgrid Architecture Modeling for Control operation.

EV-Emulator Research Bed



EV Emulator – Major Components

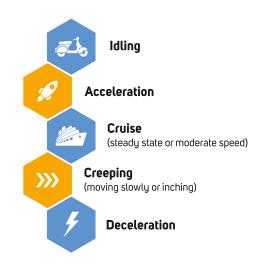
Load Emulator Propulsion Motor Specially designed for demanding EV operation Two IGBT Power Converters **Propulsion Drive WAVECT Real Time**

Supports bi-directional power flow (B2M, M2B)

Model Based Development

Powerful, Ease to use Auto Code generation Suite - Real Time Signals Software

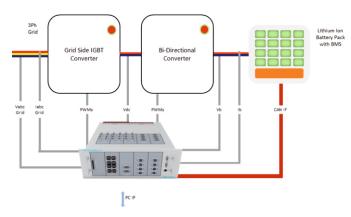
EV – Vehicle Modes



EV – Load Emulator Features



EV Battery Charging **System**



EV Battery Charging System – Key Features

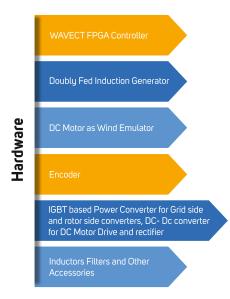


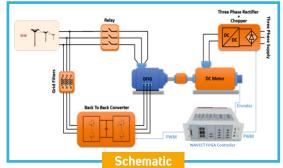
EV Battery Charging System-Major Components



Renewables

DFIG Based Wind Energy System







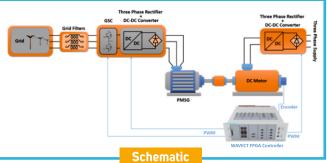
Key Functionalities

DFIG Wind Energy setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

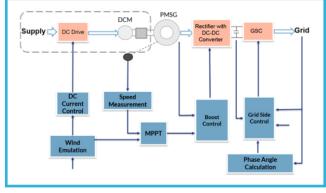
- Wind Turbine Emulation
- · Dynamic Parameters: wind velocity and pitch angle beta
- · MPPT Algorithm for Wind
- Independent Active Power(P) & Reactive Power (Q) control for Grid Side Converter(GSC)
- Rotor Side Converter(RSC) Control for sub- and super-synchronous mode operation
- Synchronization of Stator and Grid Voltages using PLL
- · Auto-isolation of emulator, generator and converters under faulty conditions.

PMSG Based Wind Energy System









Control Design

Key Functionalities

PMSG Wind Energy setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- Wind Turbine Emulation
- Dynamic Parameters: wind velocity and pitch angle beta
- MPPT Algorithm for Wind
- Independent Active Power(P) & Reactive Power (Q) control for Grid Side Converter(GSC)
 - Auto-isolation of emulator, generator and converters under faulty conditions.

Solar PV Energy System

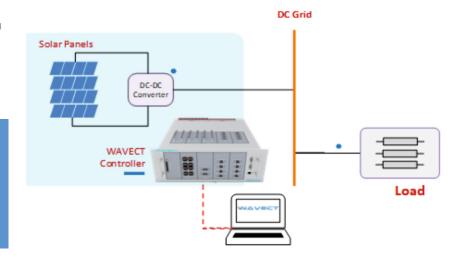
Introduction

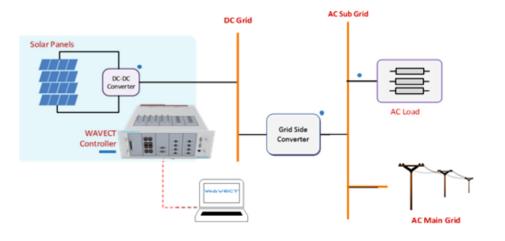
The global energy consumption is rising and an increasing attention is being paid to alternative methods of electricity generation. The very low environmental impact of the renewable energies makes them a very altractive solution for a growing demand. In this trend towards the diversification of the energy market, solar energy is a promising sustainable energy source.

Solar PV systems are generally classified into Grid-Connected, Stand alone and Hybrid Systems.

Stand-Alone PV Systems

These kind of systems are not connected to utility grid, they are self contained and are generally used in remote or rural areas



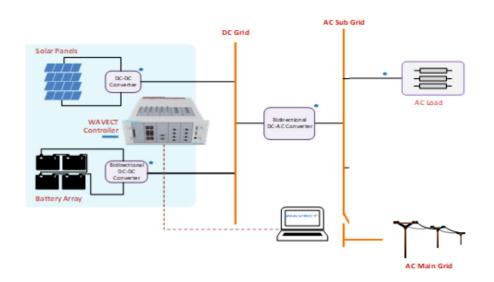


Grid Connected PV System

These type of systems are directly connected to grid via DC-AC Inverter. They are less expensive and no storage is required. In case of excess solar energy, power can be fed to grid directly and during poor weather power is supplied from AC mains and the converters can used to meet reactive power demand of the grid.

Hybrid PV systems

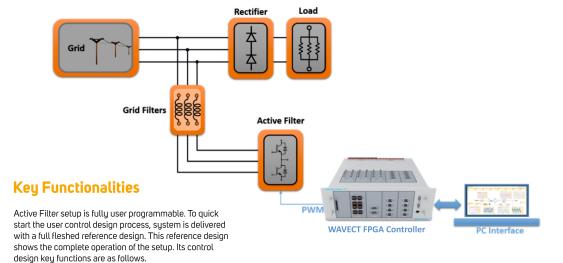
Hybrid system is the combination of above two systems, it can work as a grid connected system or as a standalone system with the help of batteries.



Power Quality

Active Filter





- Harmonics Compensation
- Reactive Power Compensation
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

Potential list of Experiments & Research scope

- Possible fault occurrences
- Statcom control development
- Unified Power Quality Conditioner control development
- Controllable DC load development
- Development of different inverter control techniques.

WAVECT FPGA Controller Rectifier + IGBT based Power Converters for DVR and Inverter AC Load Transformer Inductors Filters and Other

Accessories

Grid Emulator Grid Emulator DVR Rectifier PC Interface WAVECT FPGA Controller

Key Functionalities

DVR setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- Sag and Swell Compensation
- Provision to emulate different types of faults to DVR
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

- Possible fault occurrences
- DVR control development
- Unified Power Quality Conditioner control development.
- Different types of fault emulation development
- Development of different inverter control techniques

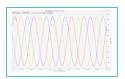
Grid Emulator

Key Functionalities

Grid Emulator setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

It can generate different types of grids:

- Three phase power grid from 0 to 440Vac
- Frequency 10 60 Hz
- · Single phase and two phases voltages for specified duration



Three phase 440 V AC



Three phase frequency

change



Single phase frequency change

Faults that can be generated:

- Voltage Sag between 60 % 90 % for specified duration
- Voltage Swell between 110 % 120 % for specified duration
- Under Voltage 60 % 90 %
- Over Voltage 110 % 120 %
- Unbalanced Voltages for specified duration







80 % Voltage Sag

110 % Voltage Swell

Unbalanced Voltages

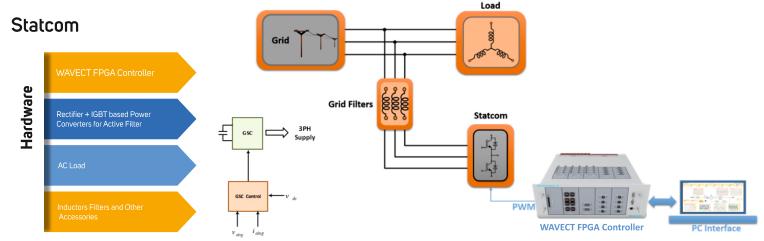
Hardware Rectifier + IGBT based Power Front End Converter and Inverter

System Potential Scope

scalable and modular, therefore there are multi-dimensional provisions to deploy the entire

Potential list of Experiments & Research scope

- Effect of possible faults at different systems. Effect of different faults at different loads.



Key Functionalities

Statcom is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as

Control Model

- · Reactive Power Compensation
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

System Potential Scope

therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

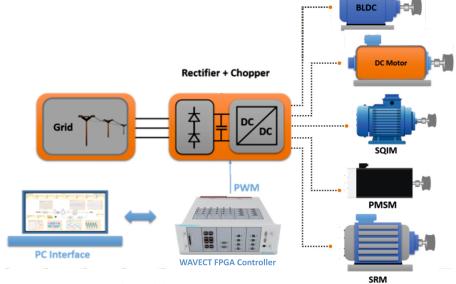
- Unified Power Quality Conditioner control development
- Controllable AC load development.

Drives

BLDC Drive

Rectifier + IGBT based Power Converter for Inverter

BLDC Motor With Mechanical Loading



System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

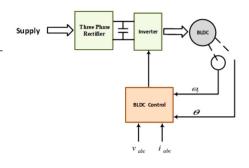
Potential list of Experiments & Research scope

- Commutation Table based Speed Control of BLDC
- Closed loop Speed Control of BLDC
- Current Controlled Operation of BLDC
- Sensor less Control of BLDC motor
- BLDC Drives with Renewables Integration
- Direct Torque control of BLDC
- Back Emf waveform estimation
- Regenerative braking
- Four quadrant operation of BLDC Drive
- Torque ripple Minimizations

Key Functionalities

BLDC Drive setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- · Voltage Mode Control.
- · Sensor less control
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.



DC Drive

Hardware

WAVECT FPGA Controller

Rectifier + IGBT based Power Converter for DC/DC converter

Separately Excited DC

Motor with Mechanical Loading

Key Functionalities

DCM Drive setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- Open loop Control.
- Closed loop Control.
- Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

- Open Loop control of DC Moto
- Closed Loop Armature Voltage control of DC Motor
- Designing Buck converters schemes for DC Motor Drive
- Field Voltage control for Speed control
- Armature current control schemes for DC Motor
- Designing of Filter Inductors for Buck converter

Induction Motor Drive

Key Functionalities IM Drive setup is fully user programmable. To quick Hardware start the user control design process, system is delivered with a full fleshed reference design. This Rectifier + IGBT based Power reference design shows the complete operation of the setup. Its control design key functions are as follows. Converter for Inverter Supply [· V/F mode of operation. · Indirect vector control. · Auto-isolation of converters from the power under different faulty conditions. Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

System Potential Scope

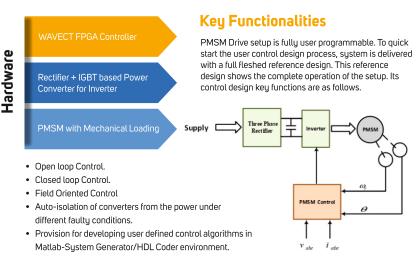
therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

Potential list of Experiments & Research scope

- Open Loop Scalar Speed Control of IM
- V/f Closed loop Speed Control of IM

- Direct Torque control of IM
 Regenerative braking
 Four quadrant operation of IM Drive

PMSM Drive



System Potential Scope

Potential list of Experiments & Research scope

- Open Loop Speed Control of PMSM
- Closed loop Speed Control of PMSM
- Direct Torque control of PMSM
- Back emf waveform estimation

SRM Drive

Hardware

Rectifier + 4 Phase IGBT based Power Converter for Inverter

SRM Motor with Mechanical

Key Functionalities

SRM Drive setup is fully user programmable. To quick start the user control design process, system is delivered with a full fleshed reference design. This reference design shows the complete operation of the setup. Its control design key functions are as follows.

- · Open loop Control.
- Closed loop Control.
- · Auto-isolation of converters from the power under different faulty conditions.
- Provision for developing user defined control algorithms in Matlab-System Generator/HDL Coder environment.

Supply

System Potential Scope

The Proposed Configuration is quite open scalable and modular, therefore there are multi-dimensional provisions to deploy the entire configuration or the individual components.

- Switching Table based Open Loop Control of SRM

WAVECT- Rapid Control Prototyping Platform

- FPGA & Dual Core ARM processor system
- Integrated Voltage and Current sensors
- Ready to use High Switching Frequency PWMs up to 2 MHz
- Control Function latency <5µs.
- High speed Analog & Digital I/O:
- Configurable Hardware Protections
- Isolated communication ports like dual CAN, dual RS485, RS232 and Gigabit Ethernet interface for PC connectivit
- Equipped with Powerful Software suite for Data Visualization, Control, Measurement and Analysis
- Dynamic parameter modification and testing



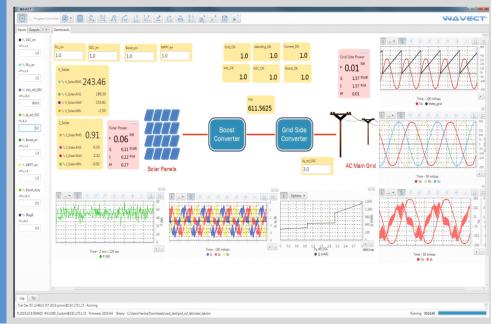
WAVECT Specifications

Controller	 Xilinx ZYNQ SoC: Dual ARM Cortex-A9 MP Core, NEON Processing/FPU Engines, Artix FPGA 512 MB DDR3, 256 MB Quad-SPI Flash and SD Card Control function execution fully on FPGA fabric Gigabit Ethernet interface
PWM Channels	 Isolated High Speed PWMs – up to 2MHz Switching Frequency with 100 steps 15V/5V Output Voltage Level – Factory option Up to 5ns PWM resolution
Voltage Sensor	 Channel to Channel Isolated Voltage Sensing +/-1000V Peak Input Range Up to 1 MSPS per channel sampling, Parallel sampling of all Channels Delta-Sigma A/D conversion: 16-bit resolution
Current Sensor	 Closed Loop Fluxgate current sensor Channel to Channel Isolated Range: 25A RMS, +/-80A Intermittent measuring range Up to 1 MSPS per channel sampling, Parallel sampling of all Channels Delta-Sigma A/D conversion: 16-bit resolution
Analog Inputs	 Channel to Channel Isolated Inputs +/-10V Peak Input Range Up to 1 MSPS per channel sampling, Parallel sampling of all Channels Delta-Sigma A/D conversion: 16-bit resolution
Analog Outputs	 +/-10V DAC Outputs, Isolated from SoC 16-bit resolution Up to 2 MSPS per channel sampling Over current Protection
Encoder Interface	 Four RS422 differential inputs per channel, Isolated from SoC +5V 0.25A power provision per channel DB15 connector per channel
Relay Interface	SPDT Relay, 250VAC, 5A switching current
Buzzer	Programmable Buzzer output
Communication Ports	 Dual CAN Ports: CAN 2.0B Ports, Signal and Power Isolated, DE9 connector Dual RS485 Ports: Full Duplex ports, Signal and Power Isolated, DE9 connector, UART RS232 Port: UART Protocol support, Signal and Power Isolated, DE9 connector
Modelling	 Powerful modelling support User selectable FPGA Sample time up to 10ns Dedicated wavect Dev Library: Model check, Easy IO block configuration and Single click binary generation Dedicated Application blockset library

WAVECT Suite **Control Tuning Analysis** 0 **Expression** Measurement **WAVECT Suite Data Logging Dashboard** Controller Mgmt **Scripting**



- FFT Panel
- Power Panel
- Energy Panel
- Power Analyzer
- Data logging



Controller Options Available

Tru-Control

- DSP + FPGA Controller
- Faster Loop time of 10µs
- High Switching Frequency up to 1MHz PWM
- Hardware Protections
- Fast test iterations & Easy Modelling

WAVECT Target

- Reduce risk and faster time to market





About us





Areas of Expertise



Mechanical



CFD



EMAG



Systems



Semiconductors



eMobility



PCB Design



PCB Proto



Additive Manufacturing



Materials



VNA



RF Solutions



Cyber Security



Internet of Things



Power Electronics

Entuple Technologies Pvt. Ltd.



2730, 'Trikannika', 80 Feet Road, HAL 3rd Stage, Indiranagar, Bangalore - 560 038



+91 806 1222 600